# **AVL** TECHNOLOGIES MODEL 1212K GLOBAL **1.2 METER MOTORIZED VEHICULAR ANTENNA**

Reflector Feed Optics **Drive System** Mount Geometry **Polarization Adjustment** 

#### **Controllers** Standard

Size

Input Power

1.2 meter AvL Carbon-Fiber Mode-matched with Rotary Joint Offset, Prime Focus, .8 f/d Patented Roto-Lok® Positioner Elevation over Azimuth Rotation of Feed



Electrical RF	Receive	<u>Transmit</u>
Frequency	10.95-12.75 GHz	13.75-14.5 GHz
Gain (Midband)		
2-port	41.6 dBi	43.2 dBi
4-port	41.5 dBi	43.1 dBi
VSWR	1.30:1	1.30:1
Beamwidth (degrees)		
-3 dB	1.3	1.2
-10 dB	2.3	2.0
First Sidelobe Level (Typical)	-22 dB	-25 dB
Radiation Pattern Compliance	>3 dB better than FCC §25.209, ITU-R S.528.5	
Antenna Noise Temperature	43° K at 30° Elevation	
Polarization	Orthogonal standard, Optional Co-pol	
Power Handling Capability	5	0.5KW per port
Cross-Pol Isolation		
On-Axis (minimum)	35 dB	35 dB
Off-Axis (within 1 dB BW)	30 dB	35 dB
Off-Axis (peak)	22 dB	30 dB
Feed Port Isolation – TX to RX	75 dB	
Satellite System Compliance	Eutelsat, Intelsat, A	siasat, PanAmSat etc.
<u>Controllers</u>		
Standard	Three-axis Jog Control & Display with Auto-stow	
Optional Upgrades		
Semi-automatic Operation	Drive to calculated position based on operator entered vehicle location, heading, plus satellite (longitude or listed)	
Automatic Operation	Drive to calculated position based on auto GPS and Flux- Gate Compass data and satellite peaking with LNB signal	
Auto-acquisition	One-button acquisition of selected satellite including peaking and optimization of cross-pol (certified for auto- commissioning on select services)	
0'		

Two Rack Units for Semi-automatic & Automatic Controllers Single Rack Unit for Auto-acquisition

110/240 VAC, 1 ph, 50/60 Hz, 6/3A peak, 1A continuous

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#### Mechanical Az/El Drive System Patented Roto-Lok® Cable Drive System **Polarization Drive System** Non back-driving Worm Gear Travel 400° Azimuth True elevation readout from calibrated inclinometer Elevation Mechanical 0° to 90° of Reflector Boresight Electrical Standard limits at 5° to 65° (CE Approval) or 5° to 90° Polarization ±95° for 2-port and 3-port Feeds ±50° for 2-port Wideband and 4-port feeds Speed Slewing/Deploying 2°/second Peaking 0.2°/second Motors 24V DC Variable Speed, Constant Torque **RF** Interface Feed Boom, Rear of Reflector, or Inside Vehicle HPA Mounting Axis Transition **Twist-Flex or Rotary Joints** WR 75 Cover Flange at Interface Point Waveguide RG59 run from feed to base plus 25 ft. (8 m) Coax 25 ft. (8 m) Cable with Connectors for Controller Electrical Interface Manual Drive Handcrank on Az and El Axii. Leads from 12VDC Pol Motor 115 to125 lbs. (52 to 57 kg) depending on options selected Weight

### **Environmental**

Stowed Dimensions

Wind	
Survival	
Deployed	75 mph (121 kmph)
Stowed	100 mph (161 kmph)
Operational	45 mph (72 kmph), Gusts to 60 mph (97 kmph)
Pointing Loss in Wind	
20 mph (32 kmph)	0.2 dB, 0.15 degrees Typical
30 Gusting to 45 mph (48 to 72 kmph)	0.8 dB, 0.30 degrees Typical
Temperature	
Operational	+5° to 125°F (-15° to 52° C)
Survival	-40° to 140°F (-40° to 60° C)

74 L x 49 W x 17 H inches (188 L x 125 W x 43 H cm)

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